

## A BETTER WAY TO CONNECT

**Industry Leading Equipment**

Stanley's CuffLink-RK offers you an elegant, fast way to adapt industry leading equipment for advanced robotic manipulation. This innovative new adapter integrates seamlessly with the award-winning Kinova arm and Robotiq's world-class adaptive robotic gripper.

**CUFFLINK-RK HIGHLIGHTS**

Created for enhanced functionality and improved aesthetics, our CuffLink-RK gives you the ability to create a beautifully designed robotic manipulator without any exposed cables or wires. Take a more polished approach and avoid the archaic use of zip ties and duct tape. More importantly, it allows you take full advantage of Kinova's infinite rotation capability and precise actuators, because there are no wires, cables, or duct tape restricting the movement of the arm.

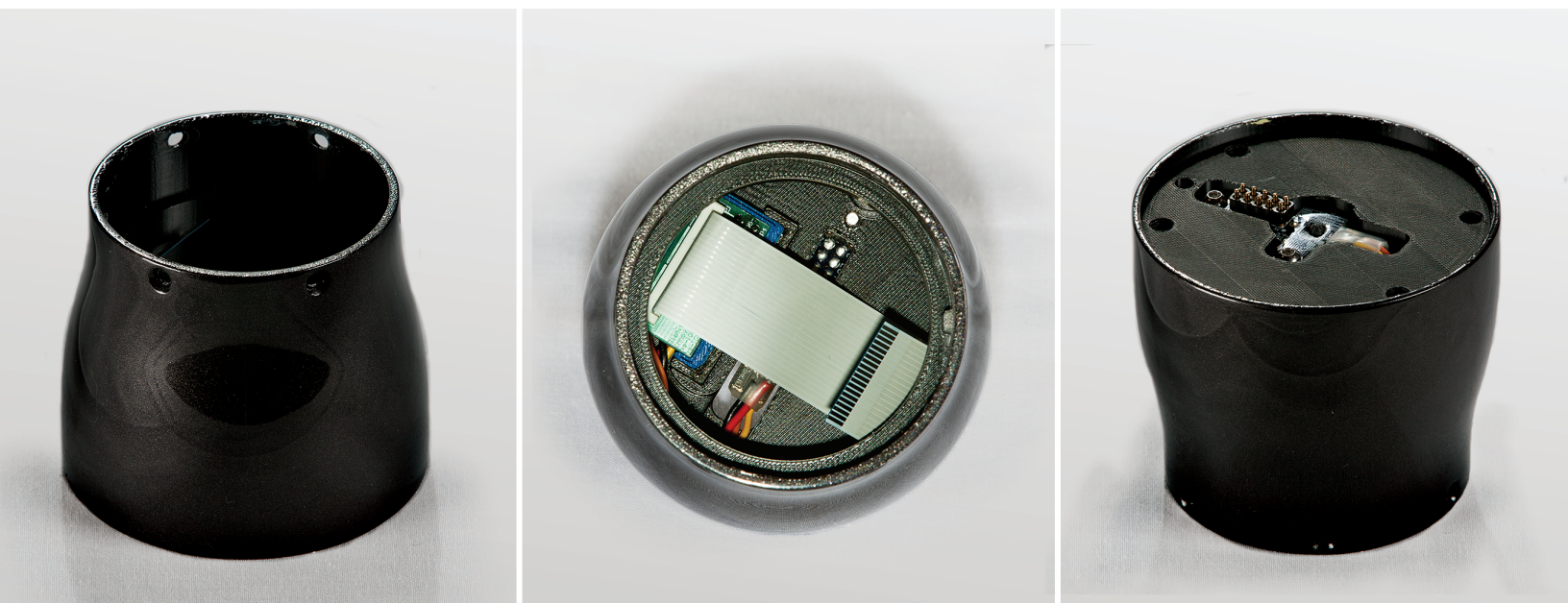
- Mates any Kinova arm with any Robotiq two-finger gripper
- Eliminates the need for externally run cable harnessing
- Eliminates restriction of the arm's range of motion
- Supports the rated payload of all Kinova arms
- CuffLink-RK supported by an open source repo
- Full simulation model including unactuated DOF
- CuffLink Installation is faster and easier than external cables
- Kinova's robot arms set the standard in service robotic manipulation. Light, compact, and power-efficient, these plug-and-play manipulators pave the way for brand new robotic applications
- Robotiq's two-finger grippers have higher grip strength, higher precision, force feedback and limiting, and an all aluminum design making them much stronger than other grippers



STANLEY ROBOTICS KEY PARTNERS



## SPECIFICATION OVERVIEW



## CUFFLINK-RK SPECIFICATIONS

MATERIAL	ABS
PAYLOAD	2.2 kg (Supports Arm Payload)
ARM COMPATIBILITY	Kinova – All Models
GRIPPER COMPATIBILITY	Robotiq – All Two-Finger Models



**CONTACT US TO LEARN MORE**

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